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Embot: an enhanced motion-based object tracker

next frame using Kalman filter then apply all tracking steps into K.V., 2000. Kalman filtering techniques for radar tracking. Electronics and Radar

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V.S.; Radar Division; LRDE Ramachandra, K.V. Abstract; Authors; of time is estimated through Kalman filtering techniques.

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Patent us5313212 - track filter bias estimation -

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Marcel Dekker, 2000, -252 pp. The Kalman filter theory published in 1960 significantly boosted the development of sophisticated digital

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A. Caya, J. Sun, and C. Snyder, 2005: A Comparison between the 4DVAR and the Ensemble Kalman Filter Techniques for Radar Data Assimilation. Mon.

A five state exponentially correlated jerk rate

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